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1. **On Processing and Registration of Forward-Scan Acoustic Video Imagery**  
Negahdaripour, S.; Firoozfam, P.; Sabzmeydani, P.;  
Computer and Robot Vision, 2005. Proceedings. The 2nd Canadian Conference  
on  
09-11 May 2005 Page(s):452 - 459  
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1. **Image based predictive display for tele-manipulation**  
Jagersand, M.;  
Robotics and Automation, 1999. Proceedings. 1999 IEEE International Conference on  
Volume 1, 10-15 May 1999 Page(s):550 - 556 vol.1  
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2. **Predictive display models for tele-manipulation from uncalibrated camera-capture of scene geometry and appearance**  
Yerex, K.; Cobzas, D.; Jagersand, M.;  
Robotics and Automation, 2003. Proceedings. ICRA '03. IEEE International Conference on  
Volume 2, 14-19 Sept. 2003 Page(s):2812 - 2817 vol.2  
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3. **Calibration-free robotic eye-hand coordination based on an auto disturbance-rejection controller**  
Jianbo Su; Wenbin Qiu; Hongyu Ma; Peng-Yung Woo;  
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Volume 20, Issue 5, Oct. 2004 Page(s):899 - 907  
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4. **Estimating workpiece pose using the feature points method**  
Nai-Yung Chen; Birk, J.; Kelley, R.;  
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Volume 25, Issue 6, Dec 1980 Page(s):1027 - 1041  
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5. **Learning, tracking and recognition of 3D objects**  
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Intelligent Robots and Systems '94. 'Advanced Robotic Systems and the Real World', IROS '94. Proceedings of the IEEE/RSJ/GI International Conference on  
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6. **Computer vision assisted virtual reality calibration**  
Kim, W.S.;  
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7. **A modular system for robust positioning using feedback from stereo vision**  
Hager, G.D.;  
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8. **Multisensory visual servoing by a neural network**  
Guo-Qing Wei; Hirzinger, G.;

Systems, Man and Cybernetics, Part B, IEEE Transactions on  
Volume 29, Issue 2, April 1999 Page(s):276 - 280  
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**9. Extended-range hybrid tracker and applications to motion and camera tracking in manufacturing systems**

Zetu, D.; Banerjee, P.; Thompson, D.;  
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**10. Machine vision system for the automatic identification of robot kinematic parameters**

Rousseau, P.; Desrochers, A.; Krouglicof, N.;  
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Volume 17, Issue 6, Dec. 2001 Page(s):972 - 978  
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**11. A calibration free analytical solution to image points path planning that ensures visibility**

Schramm, F.; Morel, G.;  
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Volume 1, 2004 Page(s):485 - 490 Vol.1  
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**12. Uncalibrated robotic 3-D hand-eye coordination based on the extended state observer**

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Volume 3, 14-19 Sept. 2003 Page(s):3327 - 3332 vol.3  
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**13. Visual servoing with independently controlled cameras using a learned invariant representation**

Sharma, R.;  
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